

Applications:

automatic clamping of dies on press rams

for dies varying in width

Function:

A pusher chain driven with an electric motor moves the rapid clamping system with it's attached clamping cylinder automatically to the clamping edge. The T-slot in the machine provides guidance for the chain and the clamping element. Clamping and unclamping of the cylinder is carried out by applying pressure to the cylinder, depending on the design. Following unclamping, the clamping element moves automatically from the clamping position into the parking position.

Special features:

- High functional safety by position monitoring and automatic travelling sequence
- Suitable for retrofit and installation in original equipment
- Tie rod made from high-strength forge steel
- No need for die standardisation (width and depth)
- Optimum utilisation of the ram area
- Clamping force of between 78 and 115 kN (other clamping forces on request)
- Central operation of all clamping elements
- Additional safety by mechanical self-locking clamp available on request

For power units
please see product group 7
For accessories
please see product group 11

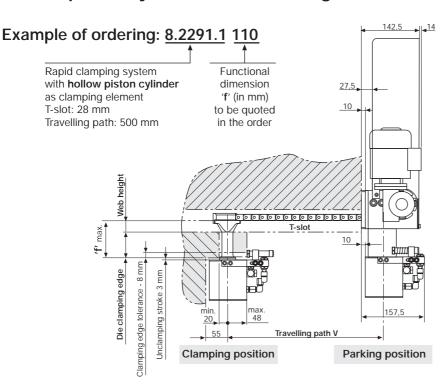


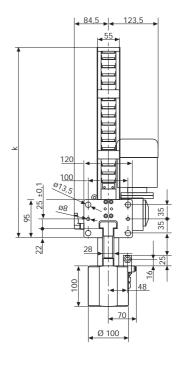
Rapid clamping system with pusher chain fastened to the press ram of a double column press. A hollow piston cylinder serves as clamping element.





Design: Hollow piston cylinder, double-acting



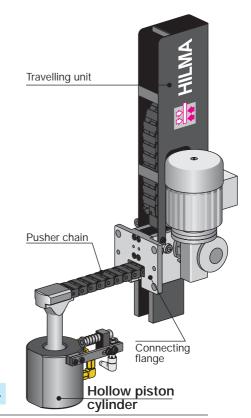


Part no.	T-slot to DIN 650 (mm)	Clamping force at 400 bar (kN)	Operating pressure (bar)	Oil consumption clamping/ unclamping (cm ³ / mm)	Travelling path V (mm)	Dimen- sion k (mm)	Clamping dimension'f' tolerance (mm)
8.2291.1xxx	28	115	400	2,9 / 3,85	500	490	-8
8.2291.2xxx	28	115	400	2,9 / 3,85	1000	730	-8

Technical data:

Travelling path V_ Travelling speed _ _____ see table DIN 650 *) Width of T-slot _ _____ 400 V / 50 Hz / 3~ *) Motor voltage_ Rated motor current ___ Motor output _ _____ 24 (10-30) V DC *) Two proximity switches ___ 1. Parking position 2. Die position 3. A further proximity switch for "End of chain " is available on request Harting HAN3HvE *) Motor connection -(plug with 500 mm cable length) _ Harting HAN10E *) Connections for proximity switches _ (plug with 500 mm cable length) Hydraulic connection ___ Union nut M 14 x 1,5 *) (free hose length 500 mm)

 $\ensuremath{^{\star}}\xspace$) other versions as well as a spindle drive are available on request.

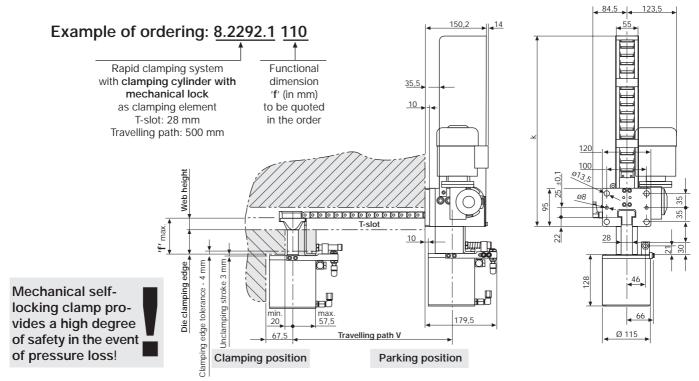


3.2291





Design: Clamping cylinder with mechanical lock, double-acting



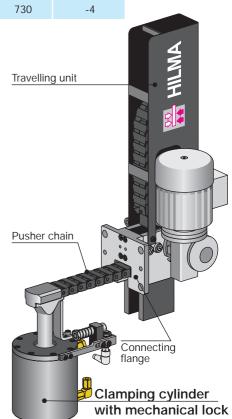
Part no.	T-slot to DIN 650 (mm)	Clamping force at 80 bar (kN)	Operating pressure (bar)	Oil consumption clamping/ unclamping (cm ³ / mm)	Travelling path V (mm)	Dimen- sion k (mm)	Clamping dimension'f' tolerance (mm)
8.2292.1xxx	28	100	80	31 / 31	500	490	-4
8.2292.2xxx	28	100	80	31 / 31	1000	730	-4

For details concerning clamping cylinders with mechanical lock, please see next page

Technical data:

Travelling path V_ Travelling speed _ _____ see table DIN 650 *) Width of T-slot _ _____ 400 V / 50 Hz / 3~ *) Motor voltage Rated motor current ___ Two proximity switches ___ _____ 24 (10-30) V DC *) 1. Parking position 2. Die position 3. A further proximity switch for "End of chain" is available on request Motor connection . Harting HAN3HvE *) (plug with 500 mm cable length) Connections for proximity switches __ Harting HAN10E *) (plug with 500 mm cable length) Hydraulic connection _ Union nut M 14 x 1,5 *)

*) other versions as well as a spindle drive are available on request.



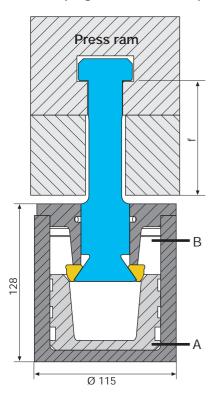
(free hose length 500 mm)



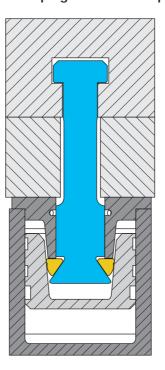


Other details: Pull-type clamping element with mechanical lock

Clamping element unclamped



Clamping element clamped



Application:

For clamping dies on the ram, the clamping force must be maintained by self-locking in the event of a hydraulic pressure drop.

Function:

The rapid clamping system moves the clamping element automatically into its clamping position. Pressure is applied to port A, the pull-type clamping element moves towards the clamping edge. Once the clamping element has come in contact with the die clamping surface, the maximum clamping power is applied, and the clamping element locks mechanically.

Mechanical self-lock ensures that the full clamping power will be maintained in the event of pressure drop.

For safety reasons, it is recommended that the hydraulic pressure is maintained.

For unclamping, relieve pressure at port A and apply pressure to port B. Following unclamping, the clamping element returns automatically into the parking position.

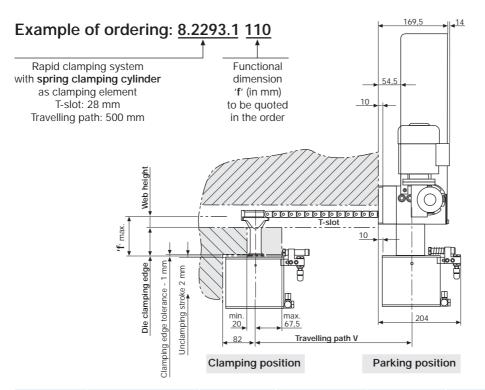
Technical data:

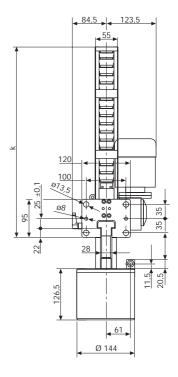
Clamping force:	100	kΝ
Max. operating pressure:	80	bar
Max. stroke:	8	mm
Positioning stroke:	3	mm
Max. clamping stroke:	4	mm





Design: Spring clamping cylinder, single-acting



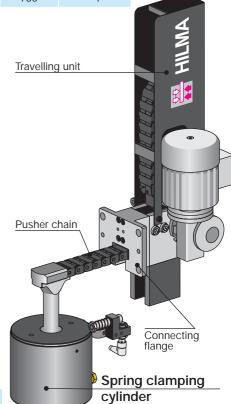


Part no.	T-slot to DIN 650 (mm)	Clamping force (kN)	Operating pressure unclamping (bar)	Oil consumption unclamping (cm ³ / mm)	Travelling path V (mm)	Dimen- sion k (mm)	Clamping dimension'f' tolerance (mm)
8.2293.1xxx	28	100	120	12,3	500	490	-1
8.2293.2xxx	28	100	120	12,3	1000	730	-1

Technical data:

Travelling path V_ Travelling speed _ see table DIN 650 *) Width of T-slot _ _____ 400 V / 50 Hz / 3~ *) Motor voltage. Rated motor current __ Motor output _ _____ 24 (10-30) V DC *) Two proximity switches _ 1. Parking position 2. Die position 3. A further proximity switch for "End of chain " is available on request Motor connection Harting HAN3HvE *) (plug with 500 mm cable length) Harting HAN10E *) Connections for proximity switches _ (plug with 500 mm cable length) Hydraulic connection ___ Union nut M 14 x 1,5 *) (free hose length 500 mm)

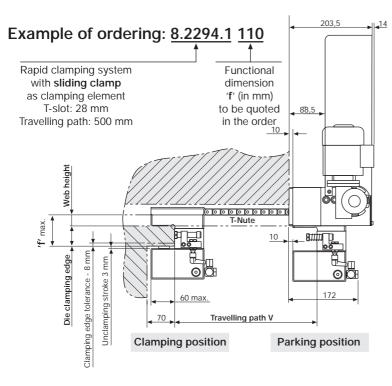
*) other versions as well as a spindle drive are available on request.

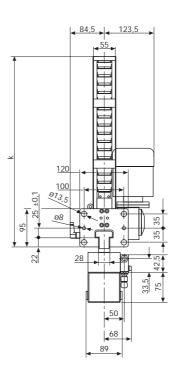






Design: Sliding clamp, single-acting

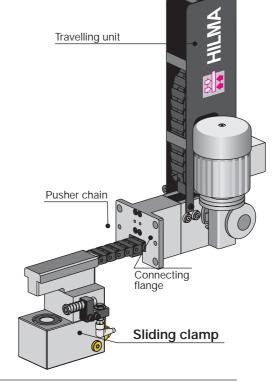




Part no.	T-slot to DIN 650 (mm)	Clamping force at 400 bar (kN)	Operating pressure (bar)	Oil consumption clamping (cm ³ / mm)	Travelling path V (mm)	Dimen- sion k (mm)	Clamping dimension'f' tolerance (mm)
8.2294.1xxx	28	78	400	1,5	500	490	-8
8.2294.2xxx	28	78	400	1,5	1000	730	-8

Technical data:

Travelling path V_ Travelling speed _ Width of T-slot _ _____ 400 V / 50 Hz / 3~ *) Motor voltage_ Rated motor current __ Motor output -_____ 24 (10-30) V DC *) Two proximity switches __ 1. Parking position 2. Die position 3. A further proximity switch for "End of chain " is available on request Harting HAN3HvE *) Motor connection . (plug with 500 mm cable length) _ Harting HAN10E *) Connections for proximity switches __ (plug with 500 mm cable length) Hydraulic connection ___ Union nut M 14 x 1,5 *) (free hose length 500 mm)



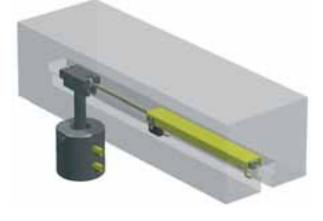
*) other versions as well as a spindle drive are available on request.

Rapid clamping system with pneumatic cylinder "Pneumatic travelling clamp"

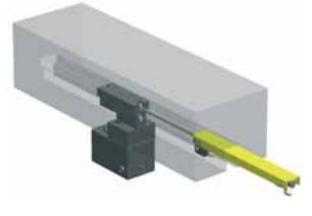


Possible clamping elements:

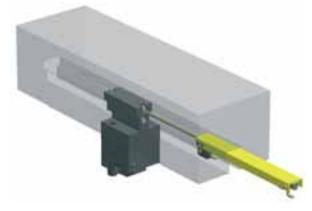
- Hollow piston cylinder double-acting with a max. clamping force of 115 kN
- Hollow piston cylinder single-acting with a max. clamping force of 104 kN
- Locking cylinder double-acting with a max. clamping force of 100 kN
- Spring clamping cylinder, single-acting with a max. clamping force of 100 kN



Sliding clamp single-acting with a max. clamping force of 78 kN



Angular clamping element single-acting with a max. clamping force of 66 kN



Application and special features:

Low-cost rapid clamping system for short distances of travel. In this version, standard clamping elements are moved by means of a pneumatic cylinder. The pneumatic positioning drive fits completely into a T-slot as per DIN 650 with a slot width of 28 mm, therefore the positioning cylinder can be positioned 'upstream' or 'downstream' of the clamping element. The positioning drive is fastened in the T-slot using a wedge lock without the need to modify the press ram. Interrogation of the unclamping and clamping positions is carried out using inductive magnetic sensors on the pneumatic cylinder.

- robust and cost-effective system for short distances of travel
- easy installation using standard clamping elements
- for fastening, no modification to the press ram is required
- rapid adaptation to various die sizes

Scope of supply:

Pneumatic positioning drive unit including screw fittings for pneumatic connection and position interrogation on the cylinder.

Clamping element

High-pressure hose and screw fittings for hydraulic connections on the clamping element

Optional extras:

- Parking station (for the unclamping position outside of the press ram)
- Travelling distance up to 400mm
- Reed contacts instead of inductive magnetic sensors
- Pneumatic one-way restrictors for adjusting the positioning speed

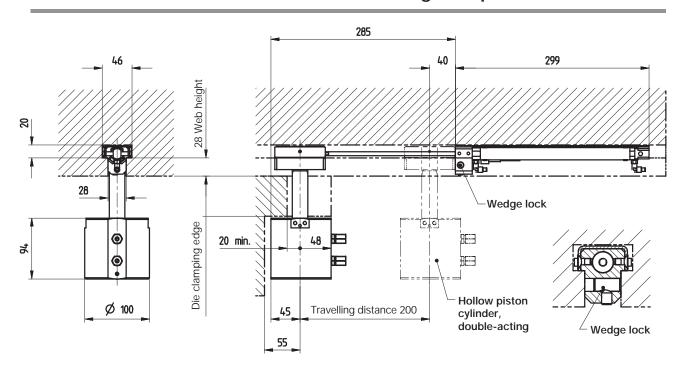
Other optional extras including adaptation are available upon request

Technical data:

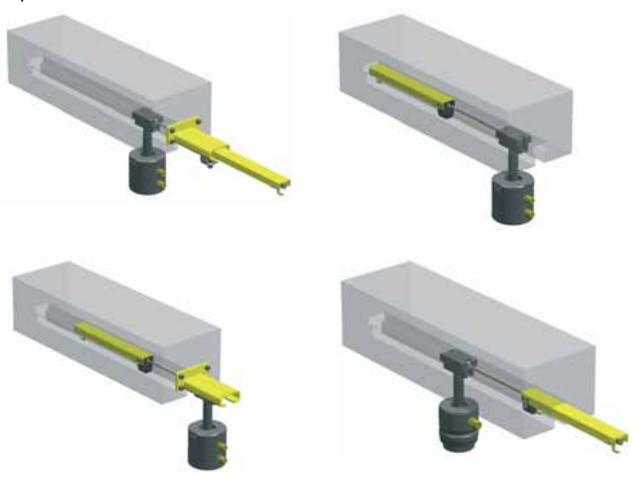
Operating pressure, pneumatic:	min. 6 bar (max. 10 bar)
Weight of the clamping element:	max. 8.5 kg (for 6 bar),
	14 kg (for 10 bar)
Travelling distance:	200 mm
Temperature range:	max. 70°C



Rapid clamping system with pneumatic cylinder "Pneumatic travelling clamp"



Optional extras and versions of installation



Product information HILMA "Force Control"



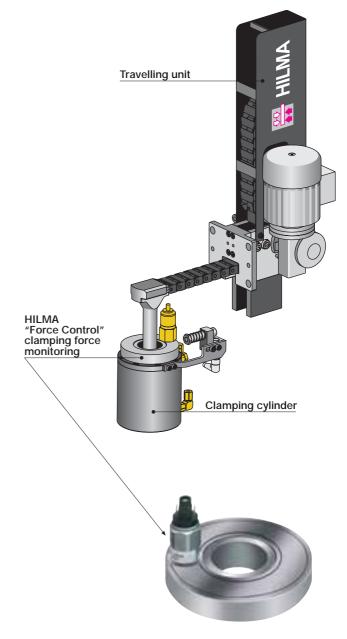
In automated die clamping systems, monitoring of the clamping position and of the clamping force is a central safety feature.

In addition to the well-known methods, i.e. monitoring of the clamping position by proximity switches and monitoring of the clamping force by pressure switches in the clamping circuit, Hilma-Römheld offers with immediate effect a new system for clamping force monitoring. The Hilma "Force Control" is designed as a loop and is installed between the clamping element and the clamping edge. "Force Control" is a closed system comprising a hydraulic piston and cylinder. The internal pressure increases and decreases in proportion to the clamping force.

By means of a pressure switch, the internal pressure is constantly monitored, and consequently the clamping force is monitored <u>directly</u> at the clamping point. The pressure switch trips when the pressure has dropped to 80% of the nominal clamping force. The signal must be evaluated by the machine control system. As a result, the power unit operates again for a short time, or the operation of the machine is interrupted.

Benefits to you:

- Real and permanent monitoring of the clamping force directly at the clamping point at an affordable price.
- Enhanced functional reliability is achieved by constant monitoring of the clamping force.
- In the case of mechanically locked clamping elements, a decrease of the clamping force is clearly visible by settlement. In the clamped condition, the pressure need not be maintained.
- Especially suitable for automated rapid clamping systems.

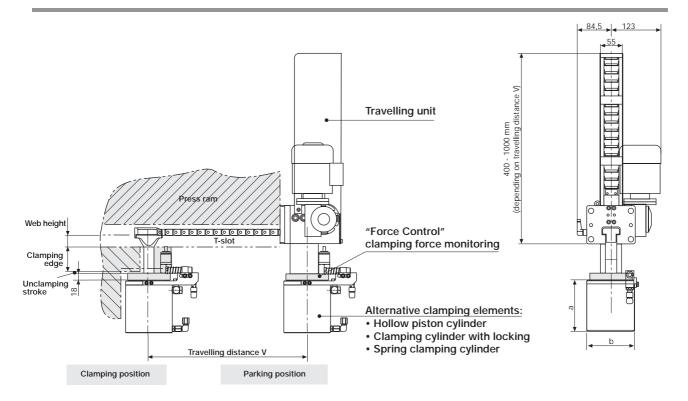




Use of rapid clamping systems with pusher chain on the press ram of a double-sided press



Product information HILMA "Force Control"



Technical data clamping element

Clamping element	Clamping force	Travelling distance	а	b
Hollow piston cylinder, double acting	115 kN at 400 bar		100	Ø 100
Clamping cylinder with locking, double acting	100 kN at 80 bar	as	128	Ø 115
Spring clamping cylinder, single acting	100 kN spring clamping force	requested	127	Ø 144

Technical data travelling unit

Travelling speed	150 mm/s
Motor voltage	400 V / 50 Hz / 3~
Nominal motor current	0,39 A
Motor output	60 W
Proximity switch	24 V DC (parking and clamping position)

Technical data "Force Control"

Installation position	any
Ambient temperature	between -25°C and 85°C
Switching element	microswitch contacts silver-coated
Voltage	24 V DC
Switching capacity	5 A inductive load
Max. switching frequency	100/min.
Electrical connection	flat-cable plug 2 x 6,3 x 0,8
Type of protection	IP 65, with protective shroud
Wiring schematics	P 1 1 Normally open contact (NO)
Part no.	8.1111.0501

